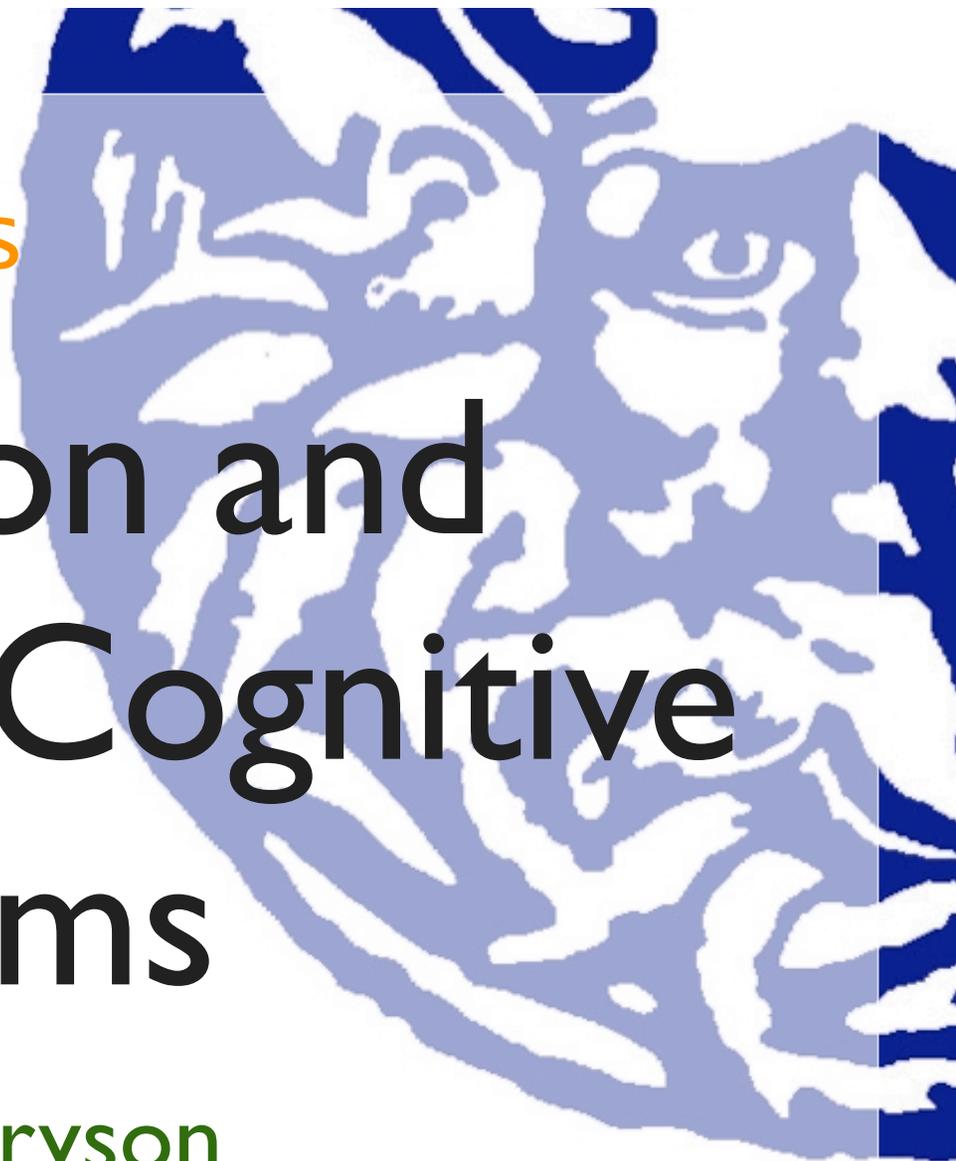


Intelligent Control  
and Cognitive Systems

# Perception and Memory in Cognitive Systems

Joanna J. Bryson

University of Bath, United Kingdom



# About the Course(work)

- Course was designed as MSc level.
- One of its deliverables is engaging you with research (both reading & writing.)
  - Informed public, citizen science.
  - Exam a concession to final-year dissertations.
- ...so, a bit about **research** (& coursework.)

# Time Management and Degree Outcomes

- Most of you are writing dissertations.
- 100 hours/course / 10 weeks/course  $\Rightarrow$  (10 hours/week - 3 hours/week lectures) \* 3 week/coursework  $\Rightarrow$  21 hours/coursework.

6 hours in lab;  
robots longest.

**~5 writing up**  $\Rightarrow$   
16 hours to hack  
and read!

# Doing Research

- 📌 First you need to get your hands dirty.
  - 📌 Learn about the problem domain.
  - 📌 Check to see whether you have an approach that might work.
- 📌 Publishable projects are normally preceded by pilot projects.

# What's Worth Doing?

- 📌 By third week, you should run with something you have.
- 📌 Normally – look at literature for controversies you might take a side on. Test which side is right.
- 📌 Google Scholar – who cited a paper you're interested in, and why?

# Writing Up Research

- Any paper can have only **one point**.
- Point is in the Intro & Conclusion. Results **prove** the conclusion; Approach & Discussion **explain** the Results.
- Pick a point / claim you think will be most promising to talk about, then examine it in detail..

# Which Point?

- 📌 What surprised you? What did you need to learn to get your robot working?
- 📌 Is there something your robot does better than the others? Could you teach others to do it?
- 📌 Look for “tricks” / lessons learned; think about the Brooks contribution.

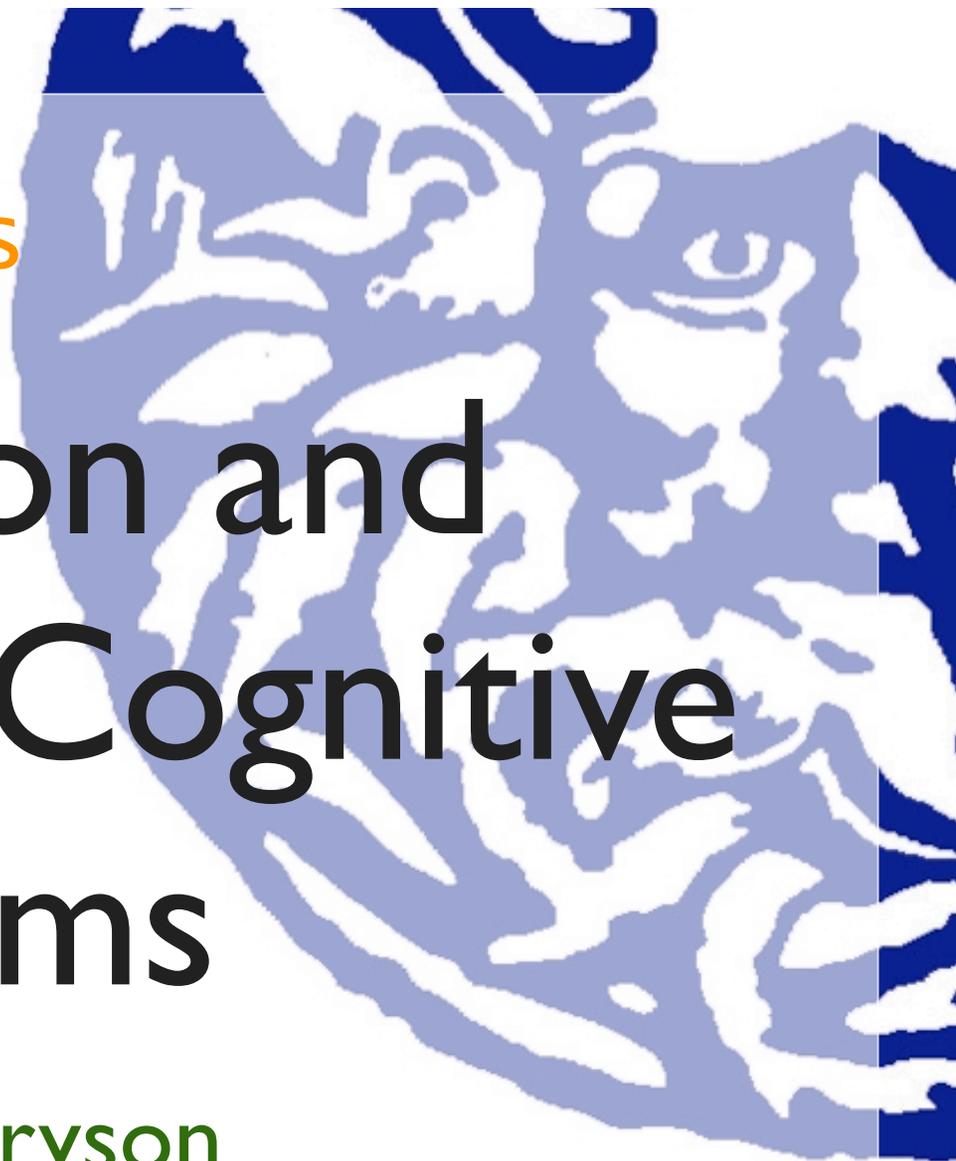
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brings you...

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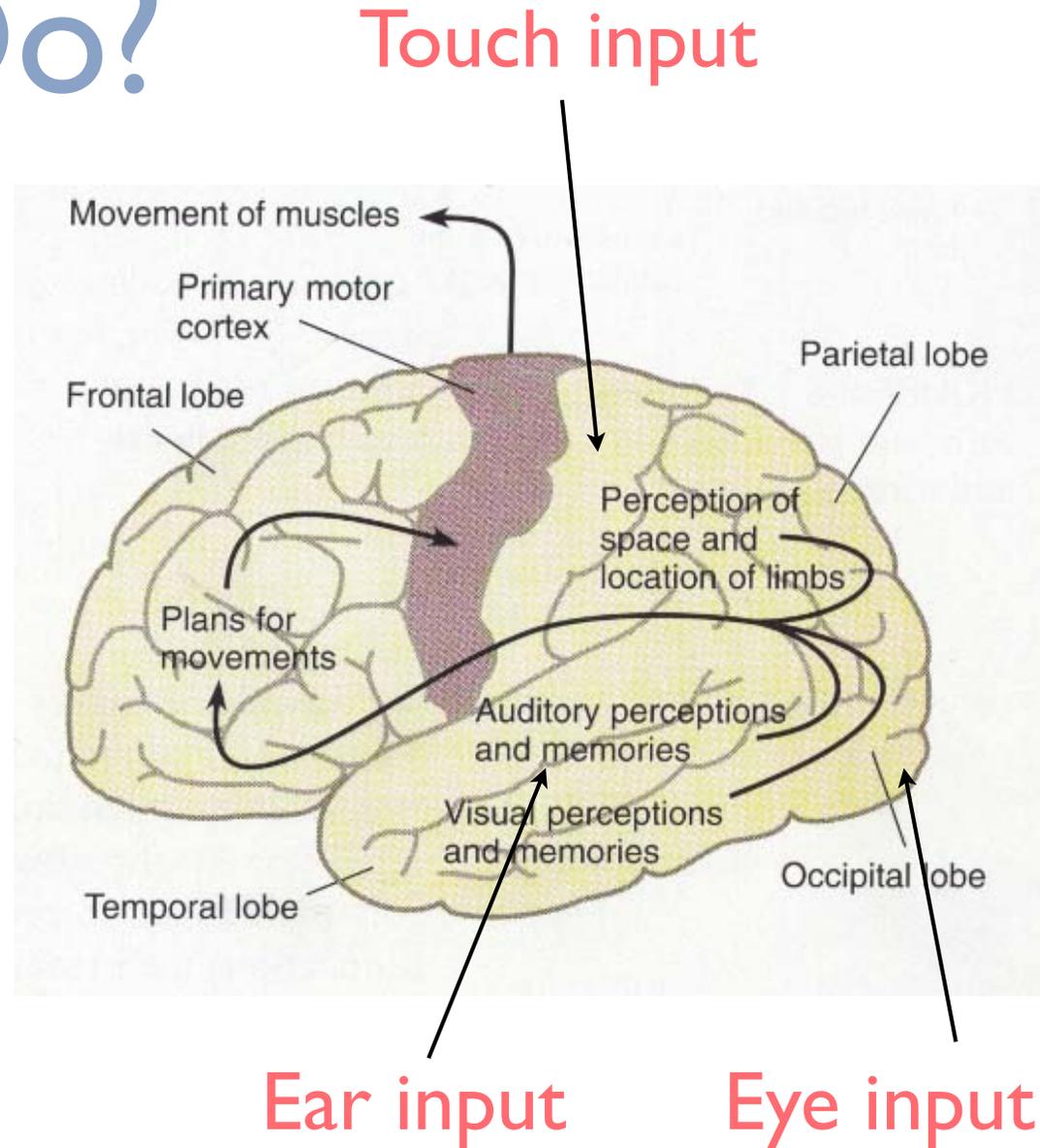
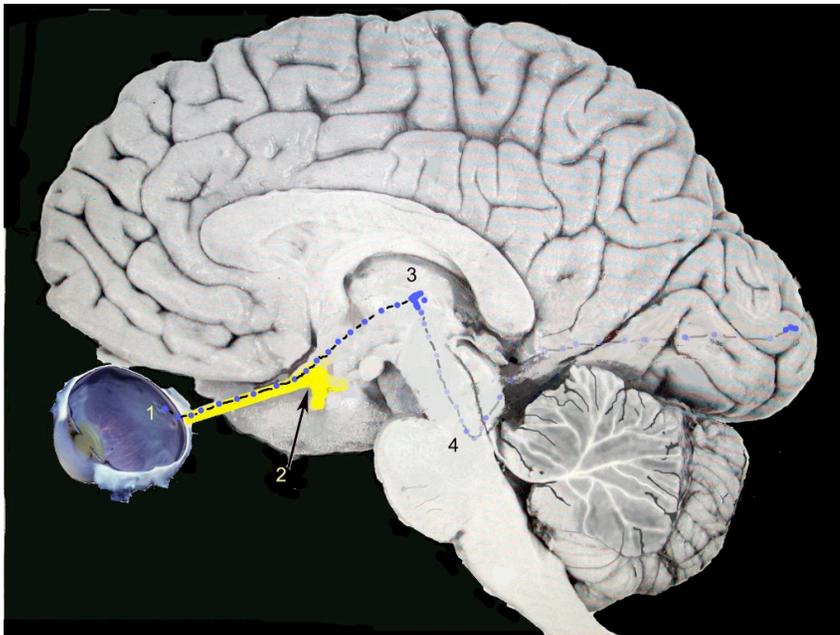
University of Bath, United Kingdom



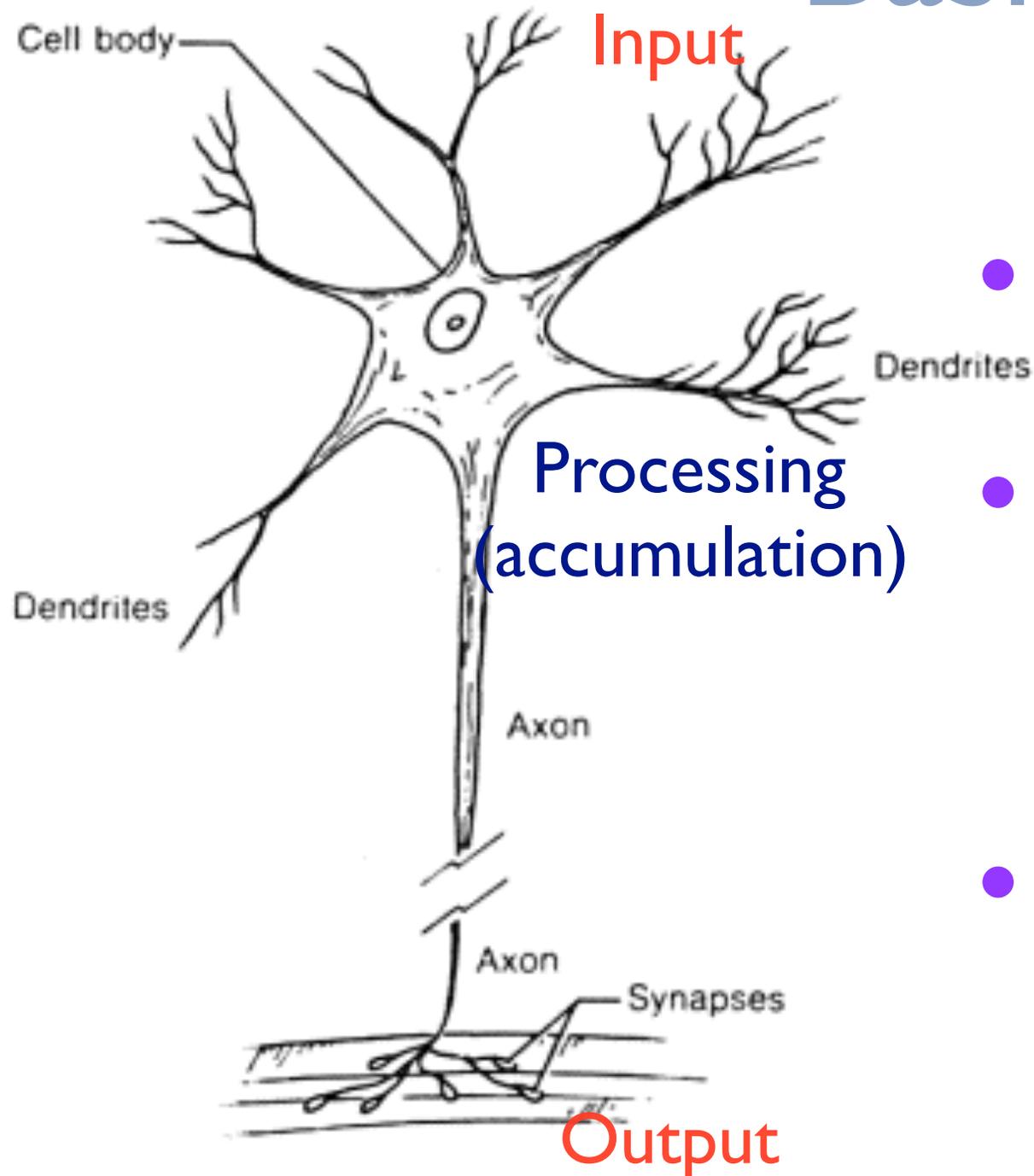
# Sensing vs Perception

- First weeks: **Sensing** – what information comes in.
- This week: **Perception** – what you **think** is going on.
  - Perception includes **expectations**.
  - Necessary for disambiguating noisy and impoverished sensory information.

# What Would Nature Do?



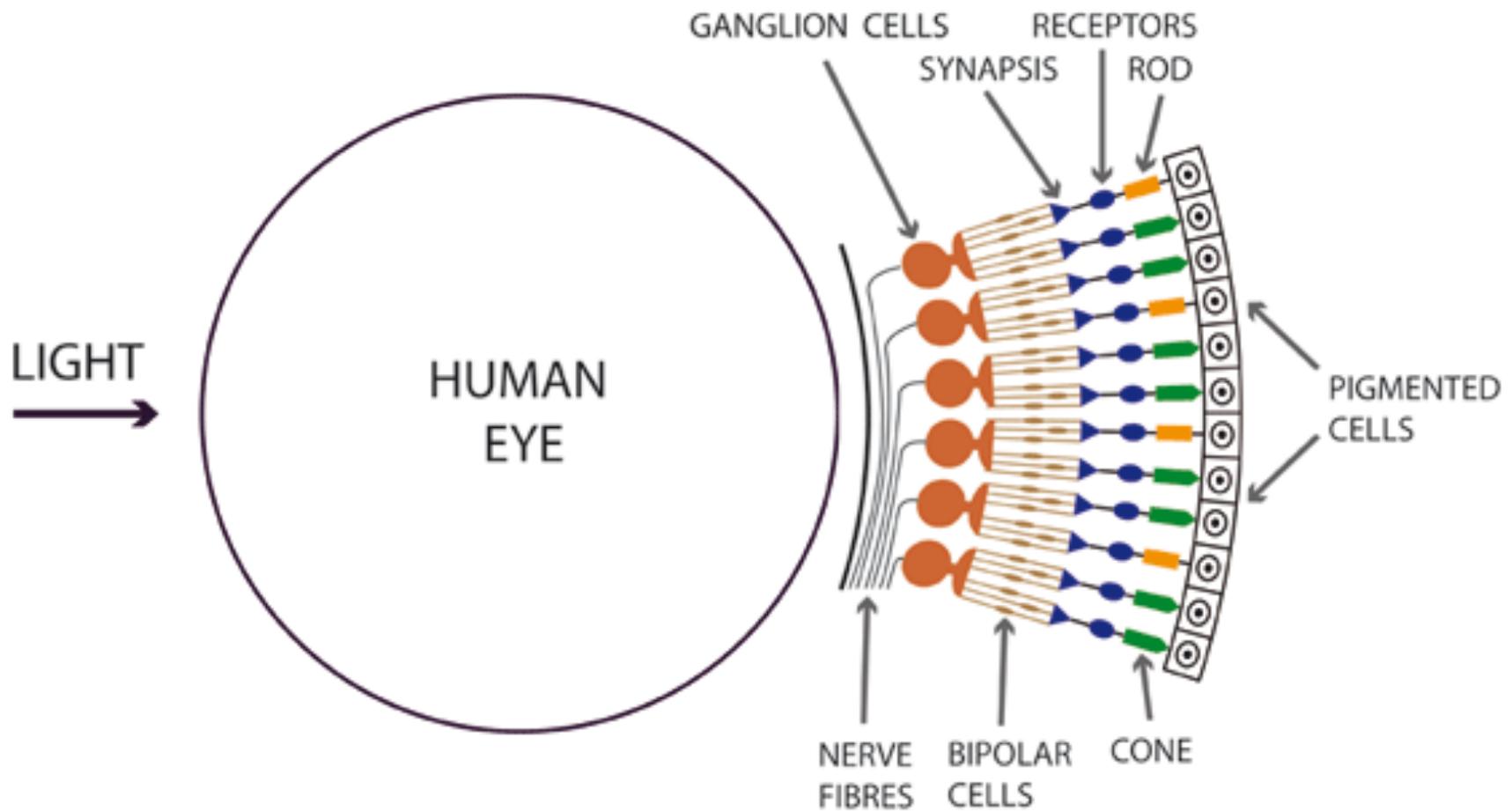
# Basic Natural CPU



- Actually whole thing computes & senses.
- Signal takes time to propagate, one cell may get two messages from same axon.
- Many different types & configurations of nerve cells.

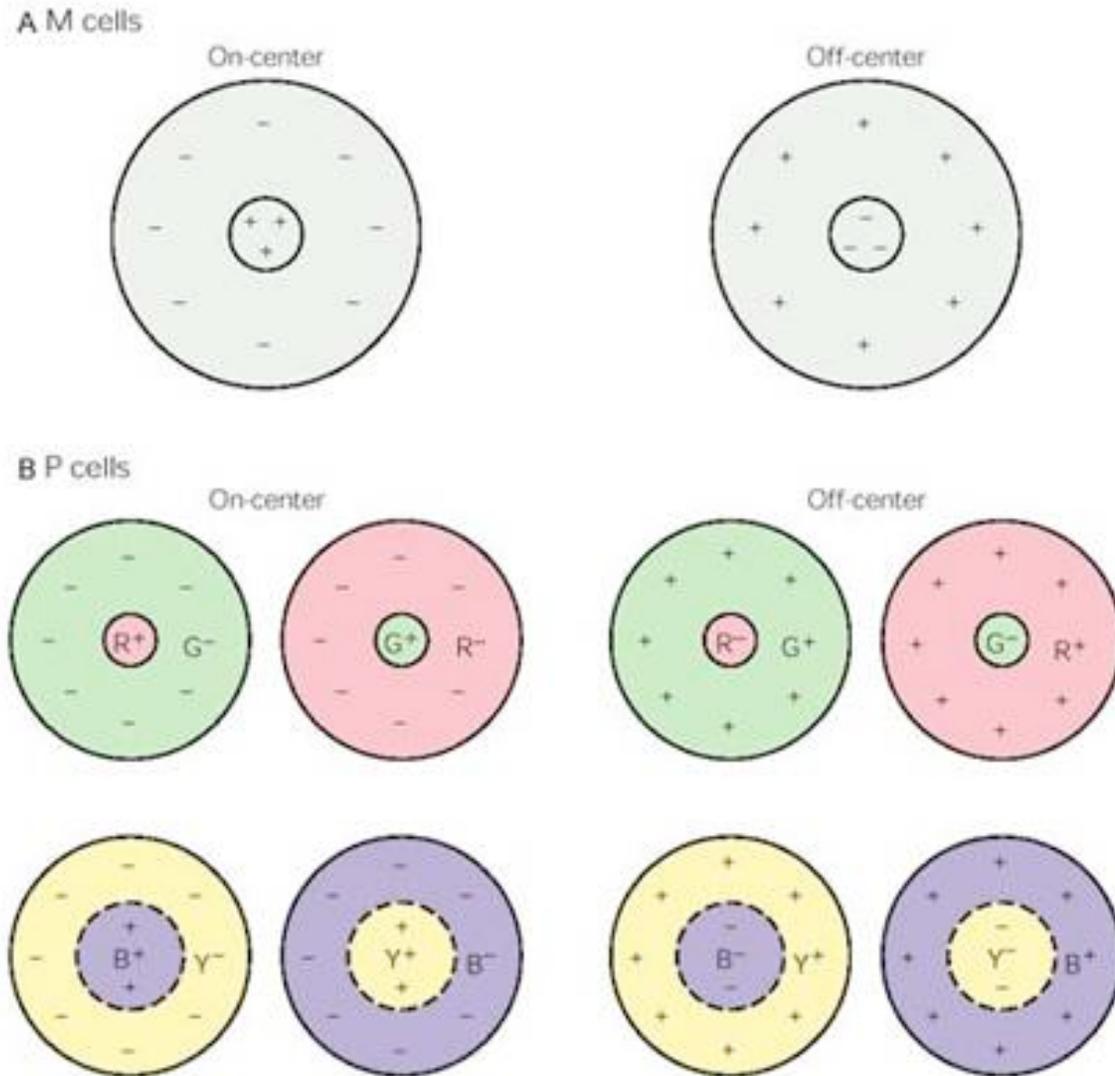
# How Eyes Work

Basic Cross section of the Eye - Showing the Rods and Cones



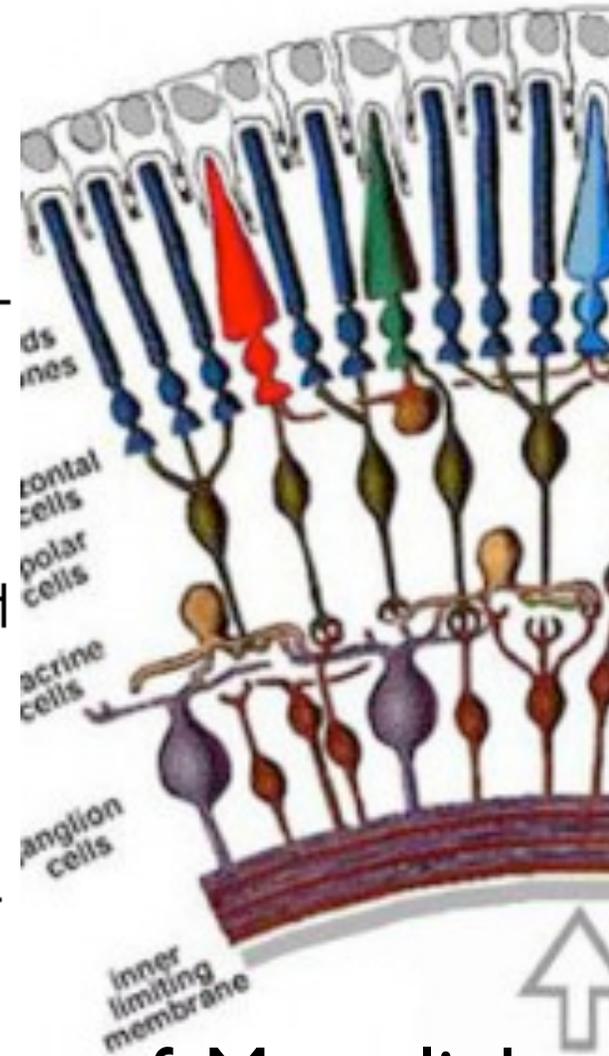
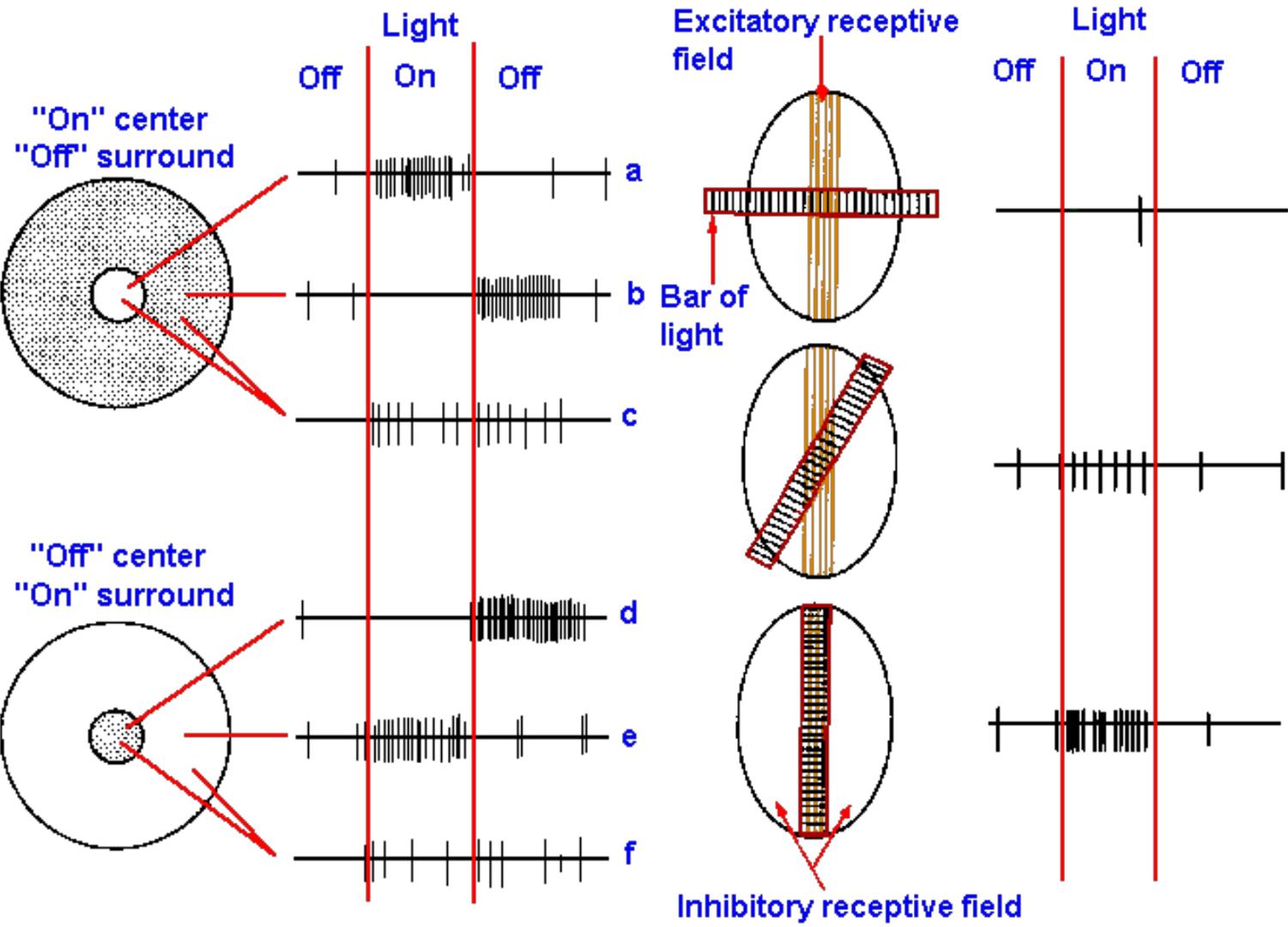
# How (Vertebrate) Eyes Work

- Lens focuses world on back of eye.
- Rods & cones (receptors) respond to light falling on them.
- Bipolar cells combine information, detect edges & gradients.
- Ganglion cells aggregate bipolar cells.



Ganglion cells detect changes in colour, brightness.  
Send this information to the back of the brain.

# Excitation, Inhibition & Feature Detection

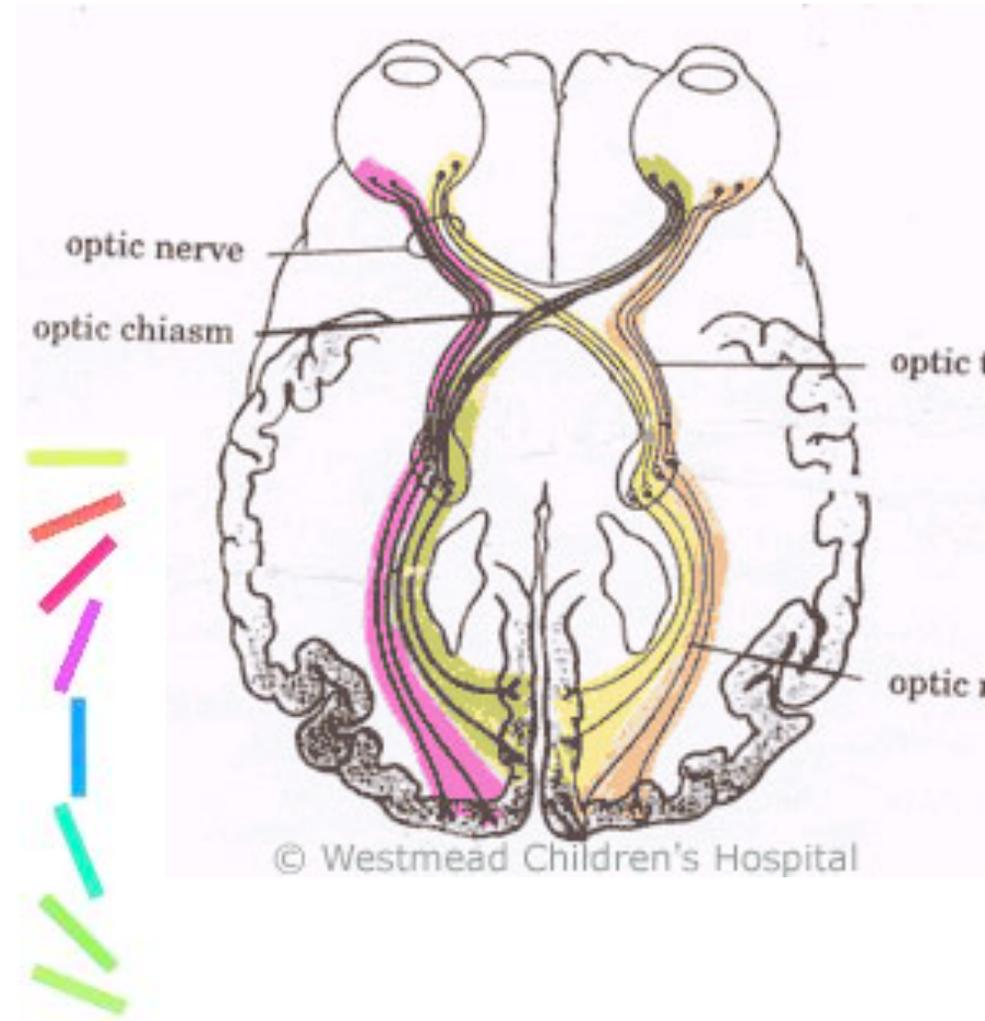
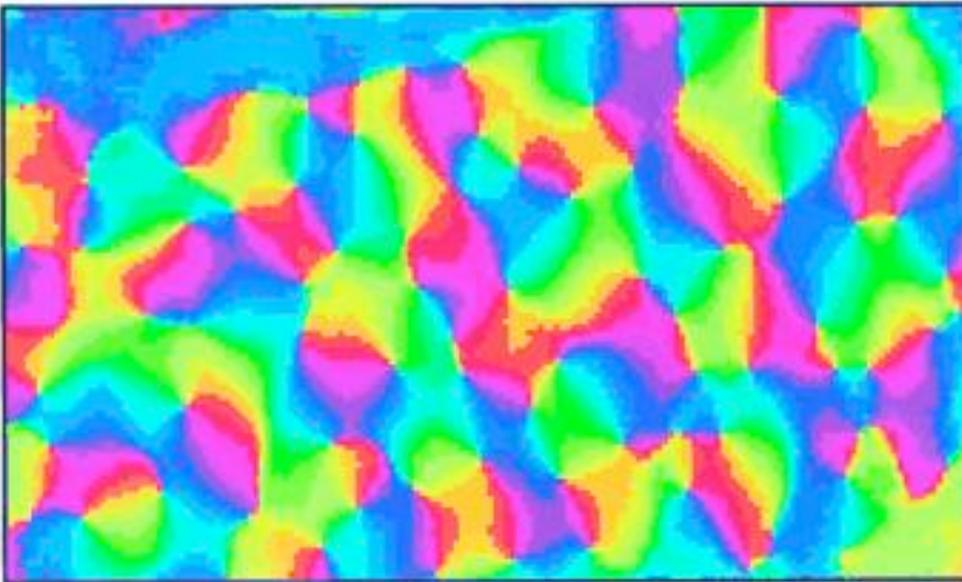


c.f. Mann link

# Information Projected and Accumulated

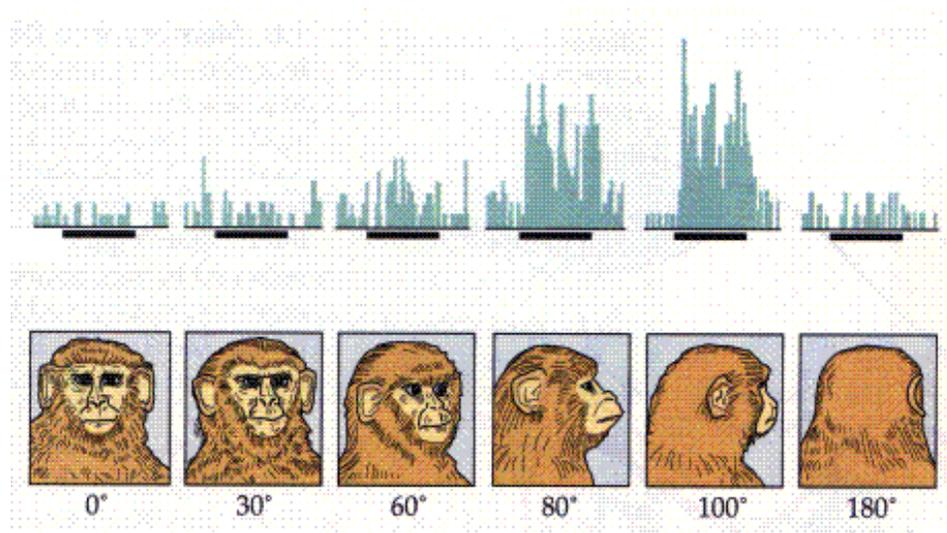
Visual cortex has retinotopic maps responding to different edges, motions.

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# Associative Cortices

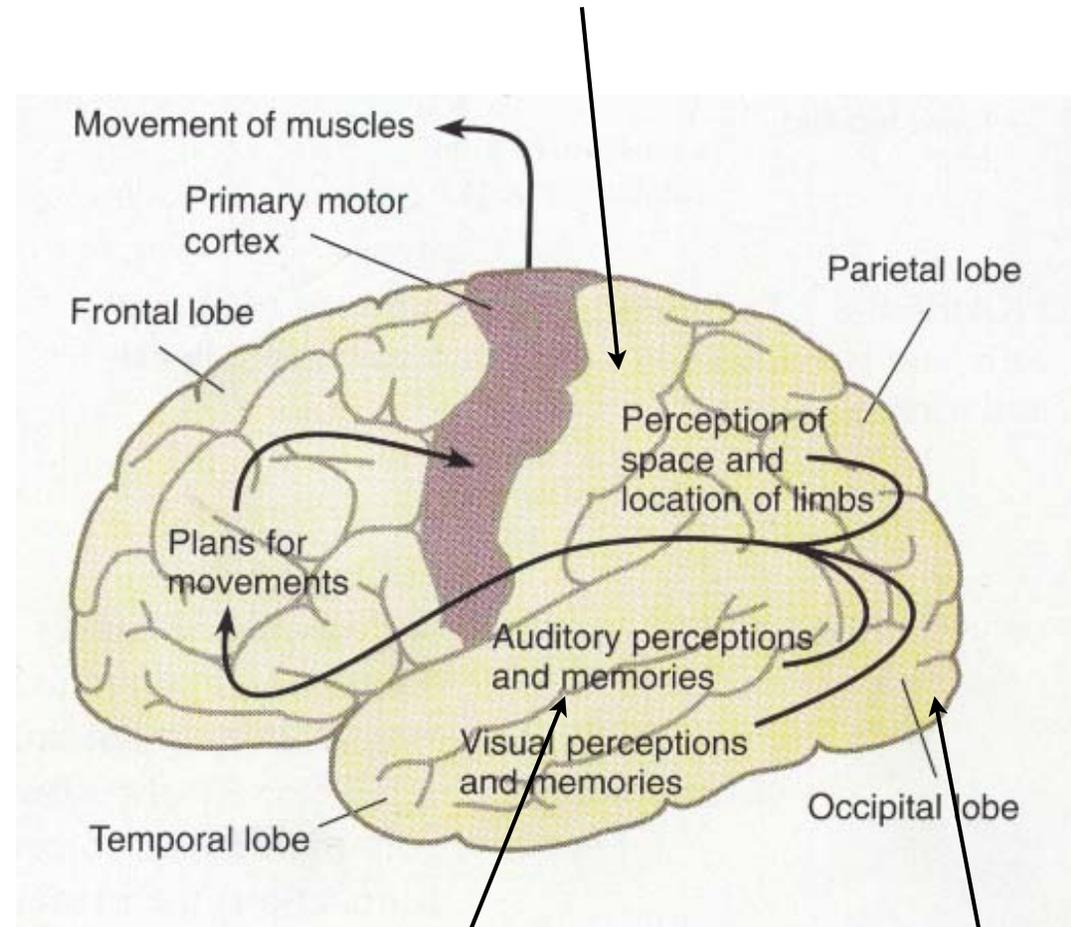
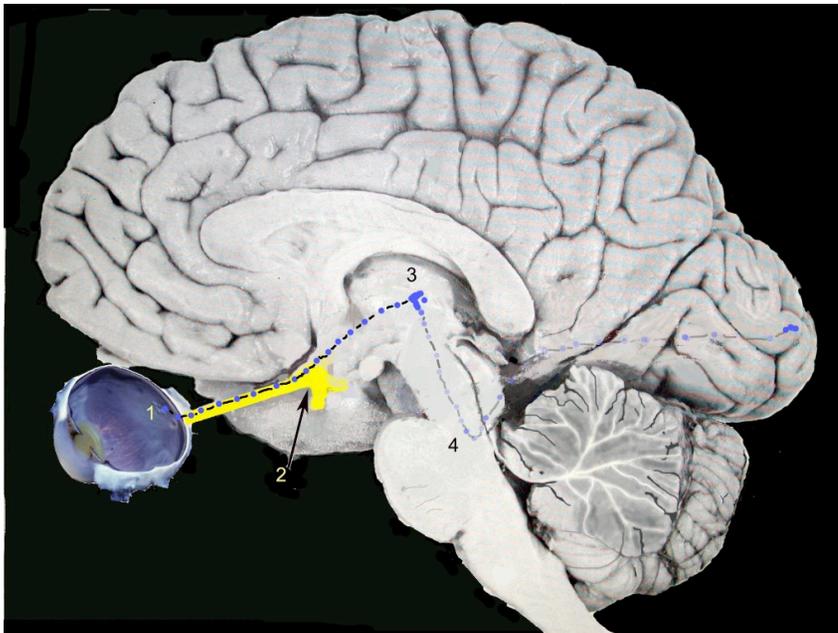
- **Features** aggregated into **objects**.
- Still in maps, e.g. for pose.
- Different systems for **what** versus **where**.



Output of a pose sensitive cell.

# Back to Perception

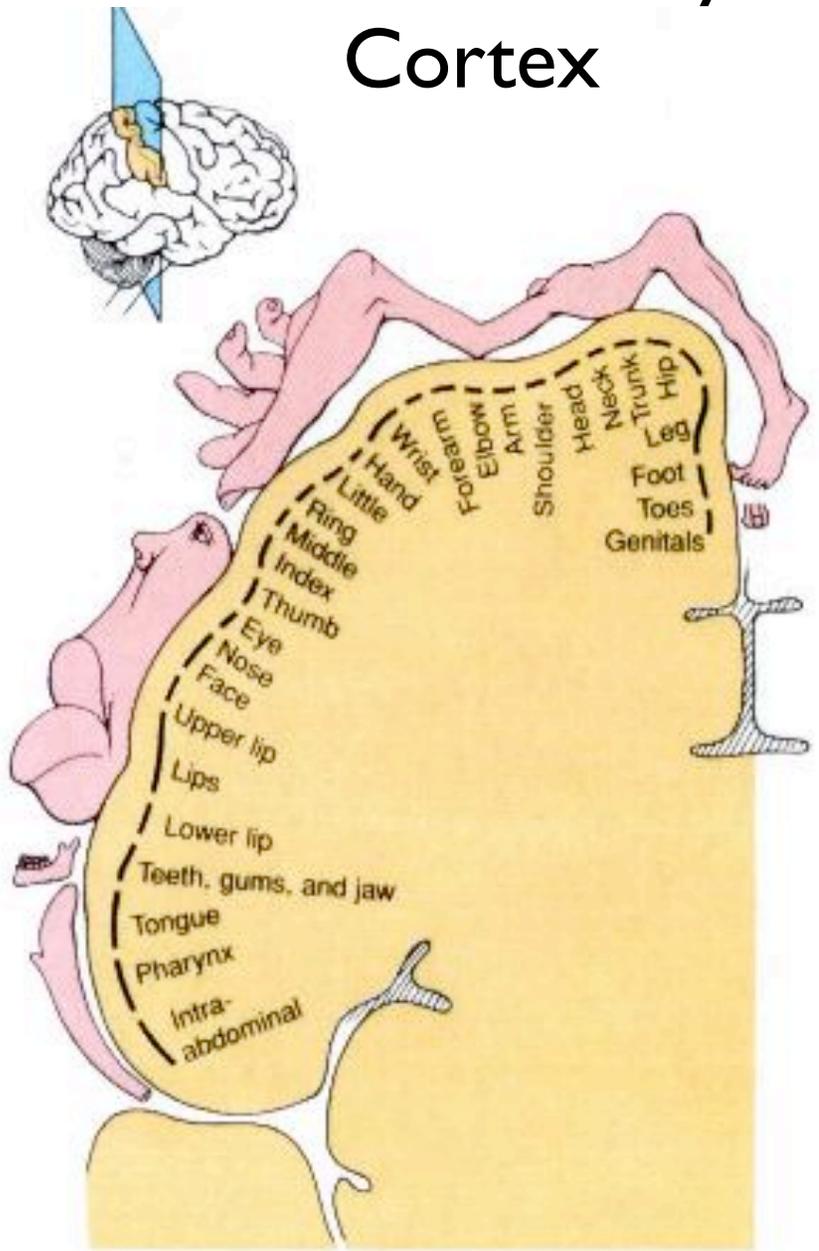
Touch input



Ear input

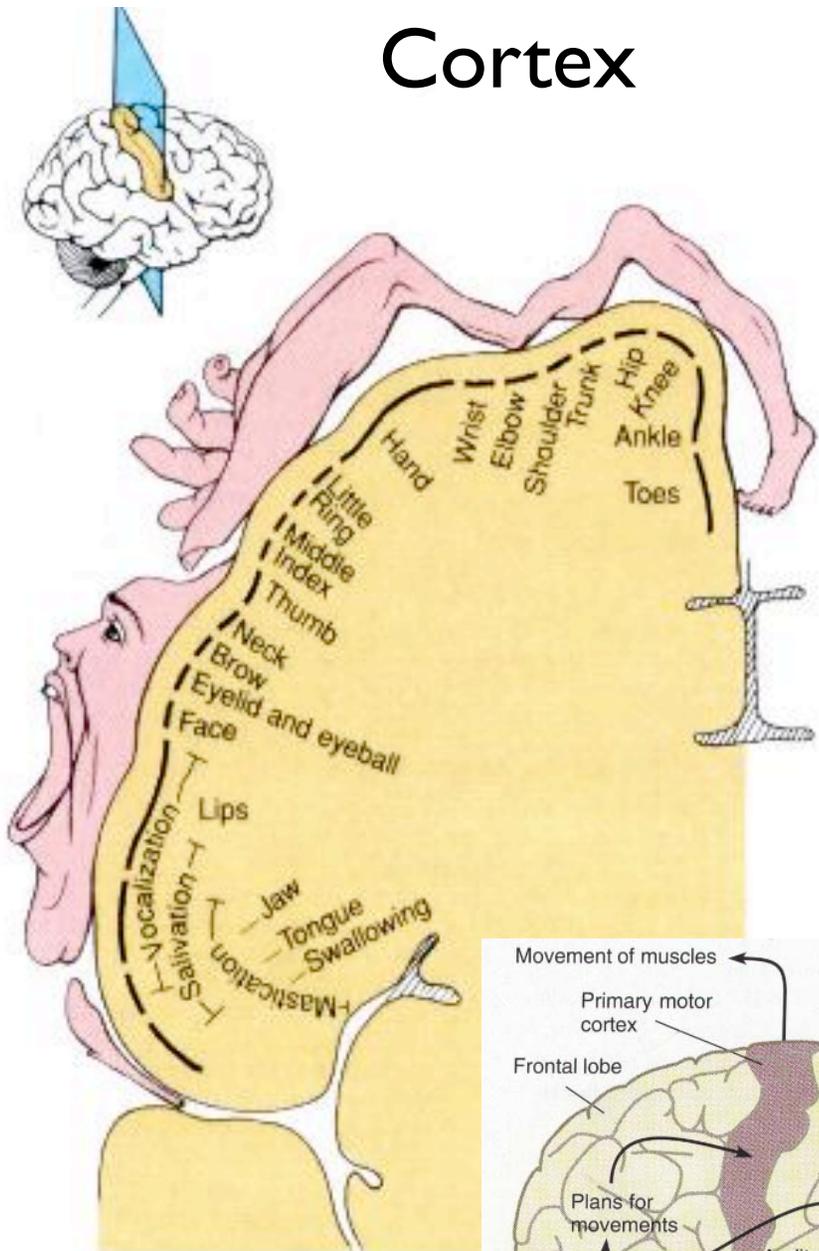
Eye input

# Somatosensory Cortex

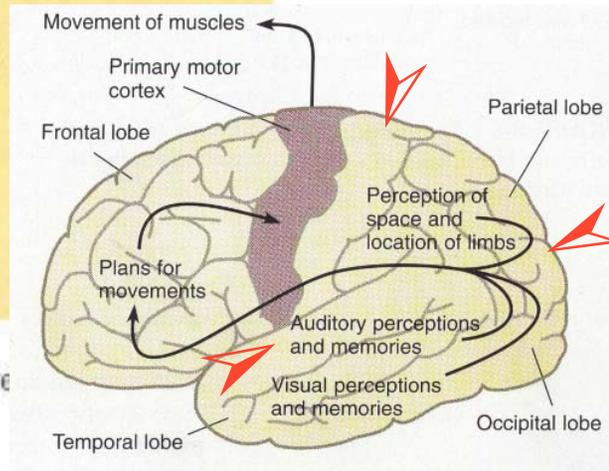


(a) Somatosensory cortex in right cerebral hemisphere

# Motor Cortex

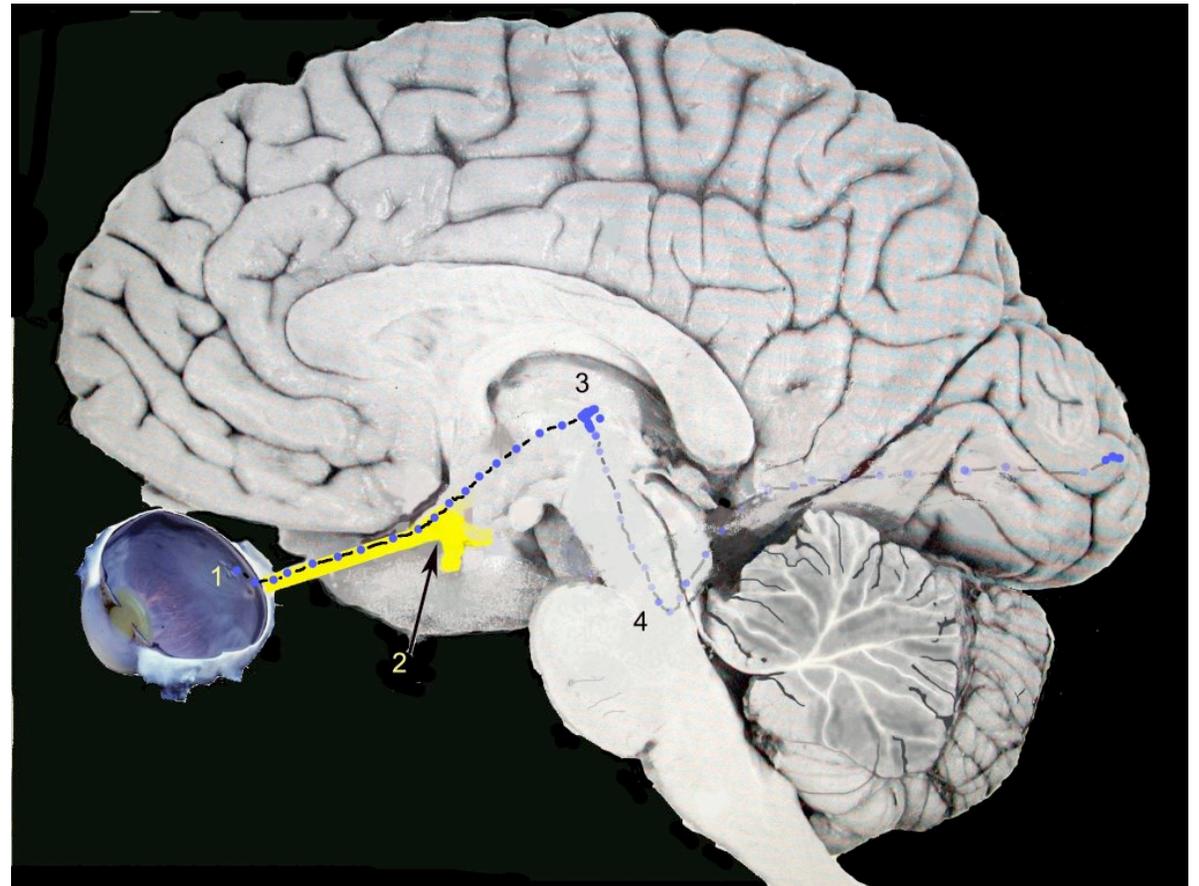


(b) Motor cortex in right cerebral hemisphere



# Brain Expectations

Up until the Thalamus → Retina connection, there are as many axons going towards the eye as away from it.



# Perception Requires Knowledge

- Sensing alone is impossible to discriminate.
- A whole lot of what the brain does is look for regularities (**co-occurrences**), then represent them.
- Nerve connections positively reinforced when both sides fire in sequence.

# The Brain's Job

## *Pattern Recognition*

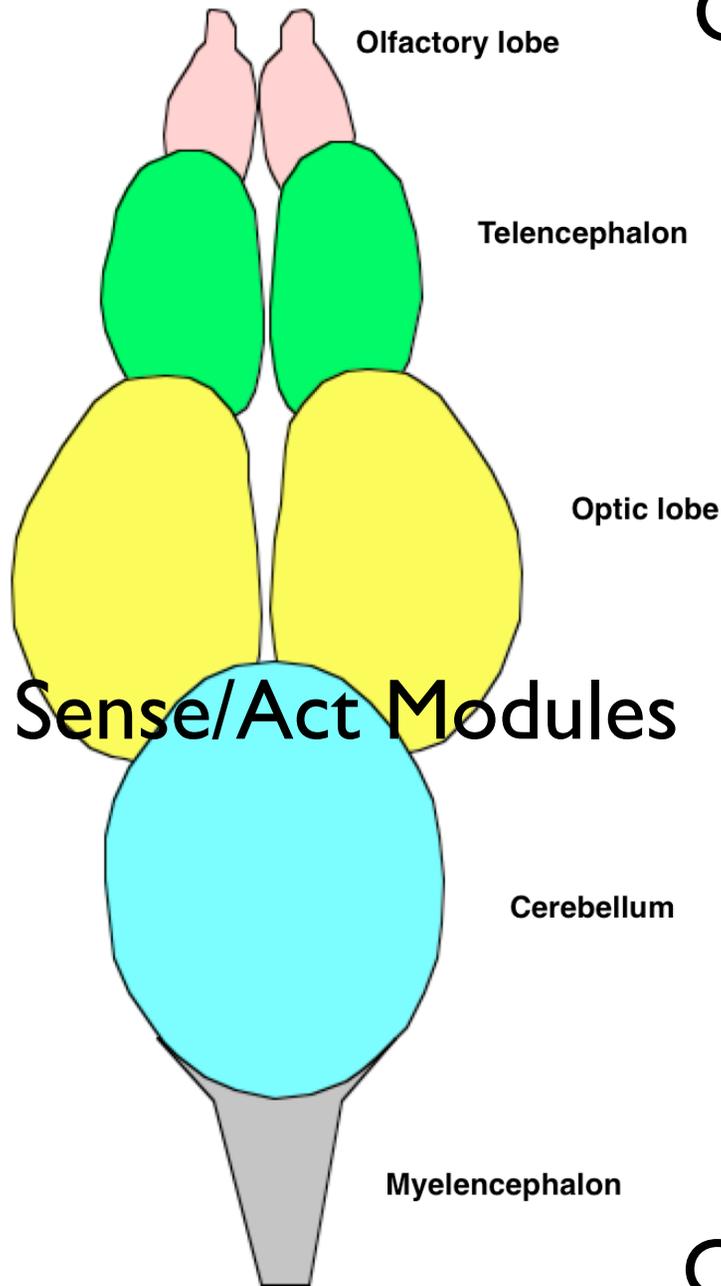
- Changing **actions** / developing **skills**,
- Discovering **concepts** / categories for **contexts** to apply actions,
- Optimising representations.

# Cognitive Architecture: Modularity

# Archetypical Real-Time AI Architecture

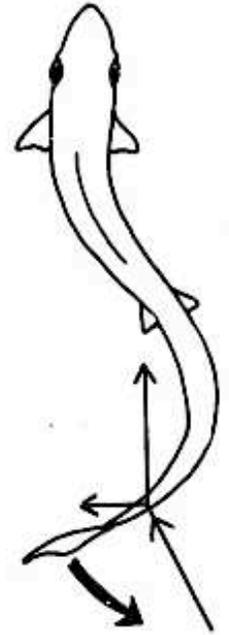
- Perception / action **modules** (bottom layer)
- Reactive (dynamic) **plans** to arbitrate between them.
- (Maybe) **planner** or at least goal **arbitration** at the top.

e.g. 3T, PRS, Soar



Goal Acquisition (smell)

Behaviour Patterns



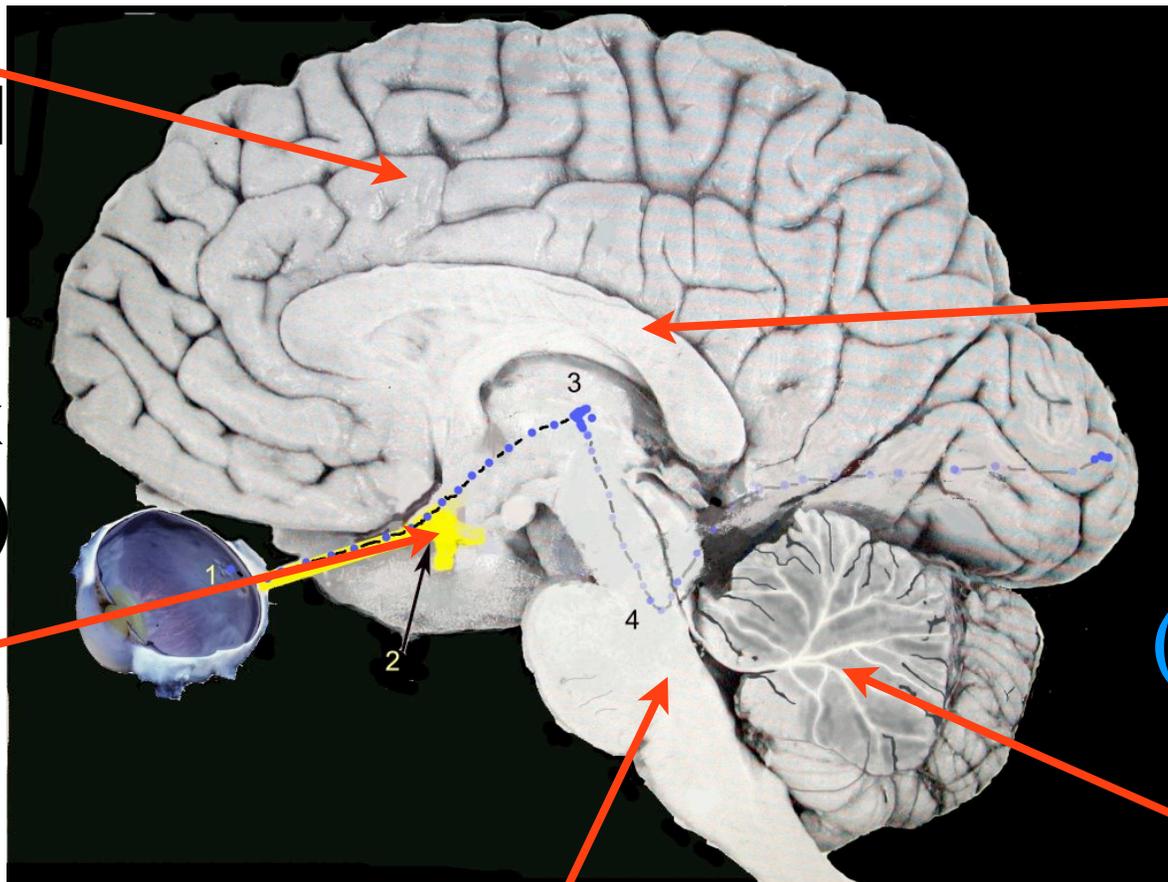
# Vertebrate (Fish) Brain as 3-Layer Architecture

Output (spinal cord)

# The Obvious Brain Modules are Functional

Long-term  
storage and  
category  
learning  
(neocortex  
/ cerebrum)

routing  
(thalamus)



episodic  
memory  
construction  
& use  
/ RAM  
(hippocampus)

smoothing  
(cerebellum)

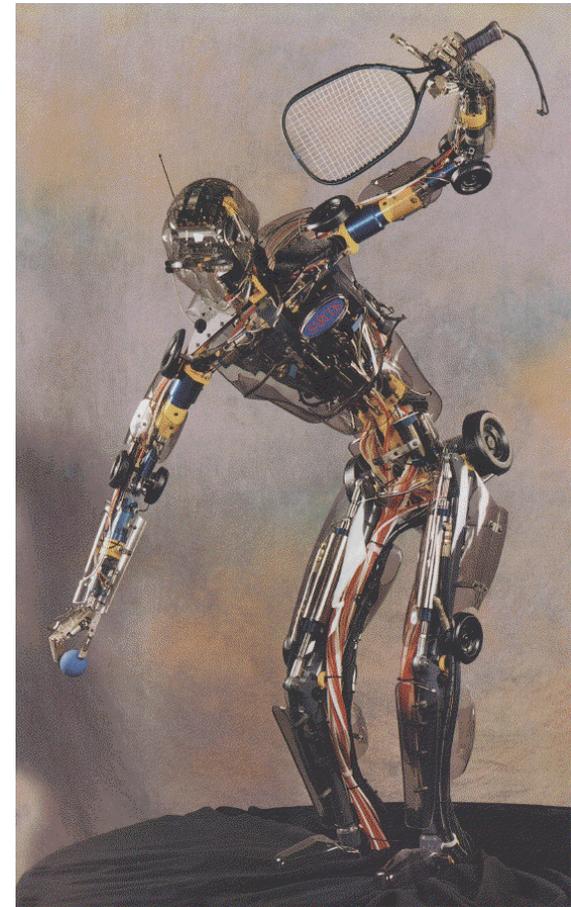
autonomic (midbrain)

# Modules in Cognitive Systems

- Many AI **cognitive architectures** separate episodic or **working memory** from **long term memory**.
- Few have the process emphasis of brain e.g. smoothing, category learning, autonomic systems. Exceptions: Ymir (Thórisson 1996).
- Brooks' sensing→action modules are **almost** ubiquitous in AI.

# Non-Modular AI

- Some researchers try to solve all AI with a single learning function.
- Can get amazing skills together this way.
- Complete systems (e.g. driverless cars) need more structure.



Atkeson, Schaal & students  
1997-2014

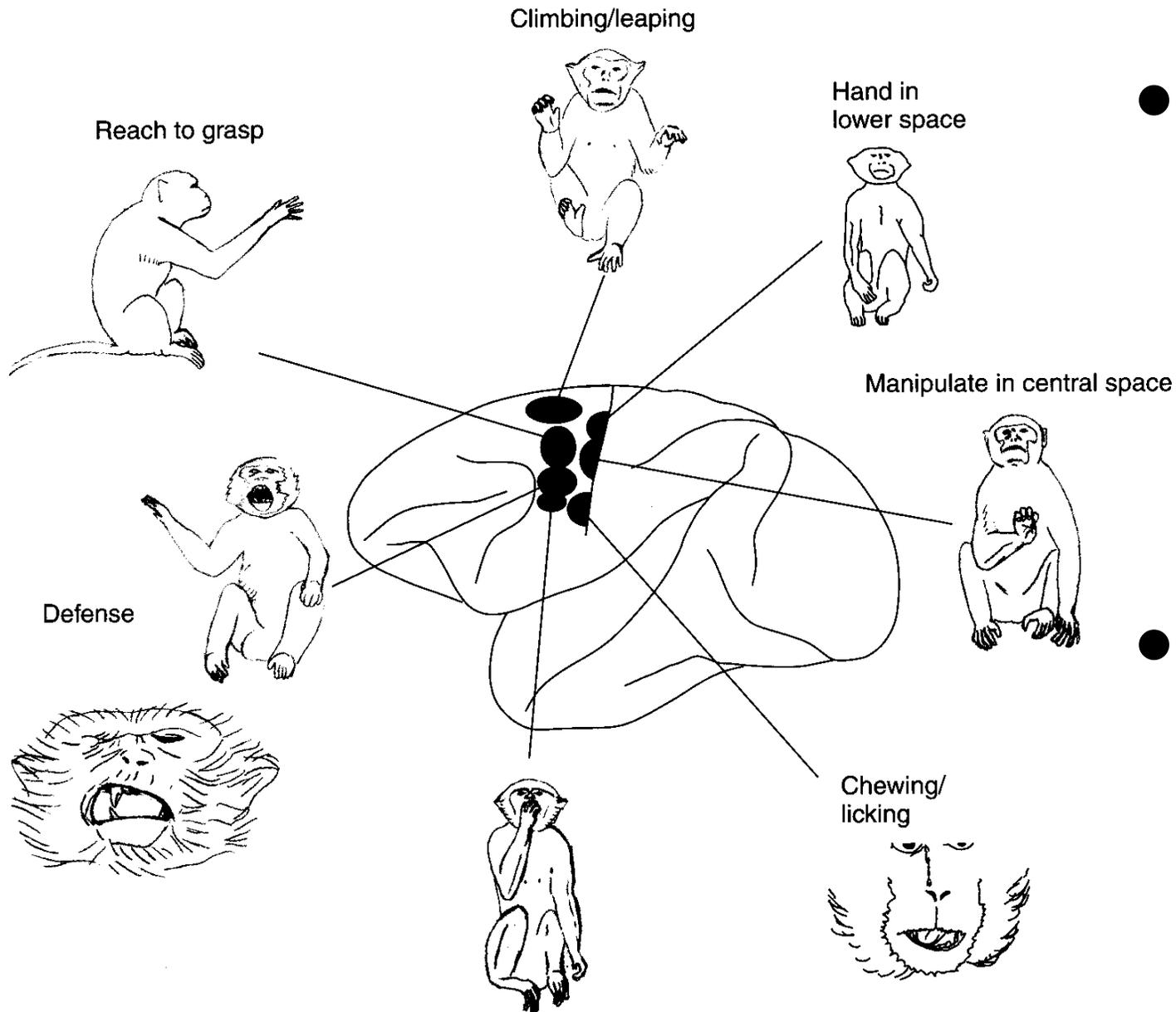
# Modularity in Cognitive Science

- Fodor (1983) describes two kinds of modules:
  - **Vertical** (sensing **or** motor skills)
  - **Horizontal** (cross-task skills like language, reasoning.)
- Brooks' (1986) are sort of super vertical (sense **and** act; cf. Minsky's agents, Society of Mind 1985).

# Perception in Nature

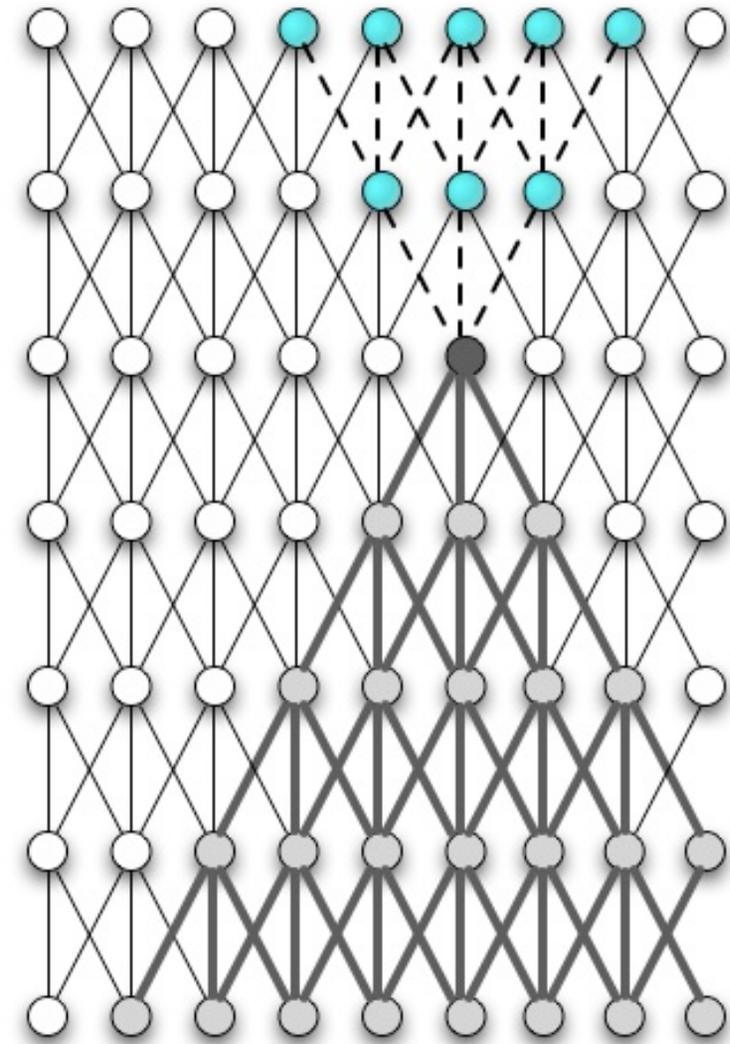
- Perception can be seen as both horizontally and vertically divided.
  - **Horizontal:** specialist mapping regions.
  - **Vertical:** Cone of perceptual processing leading to single “decision” cell coordinating descending cone of motor activation.

# Vertical Modules

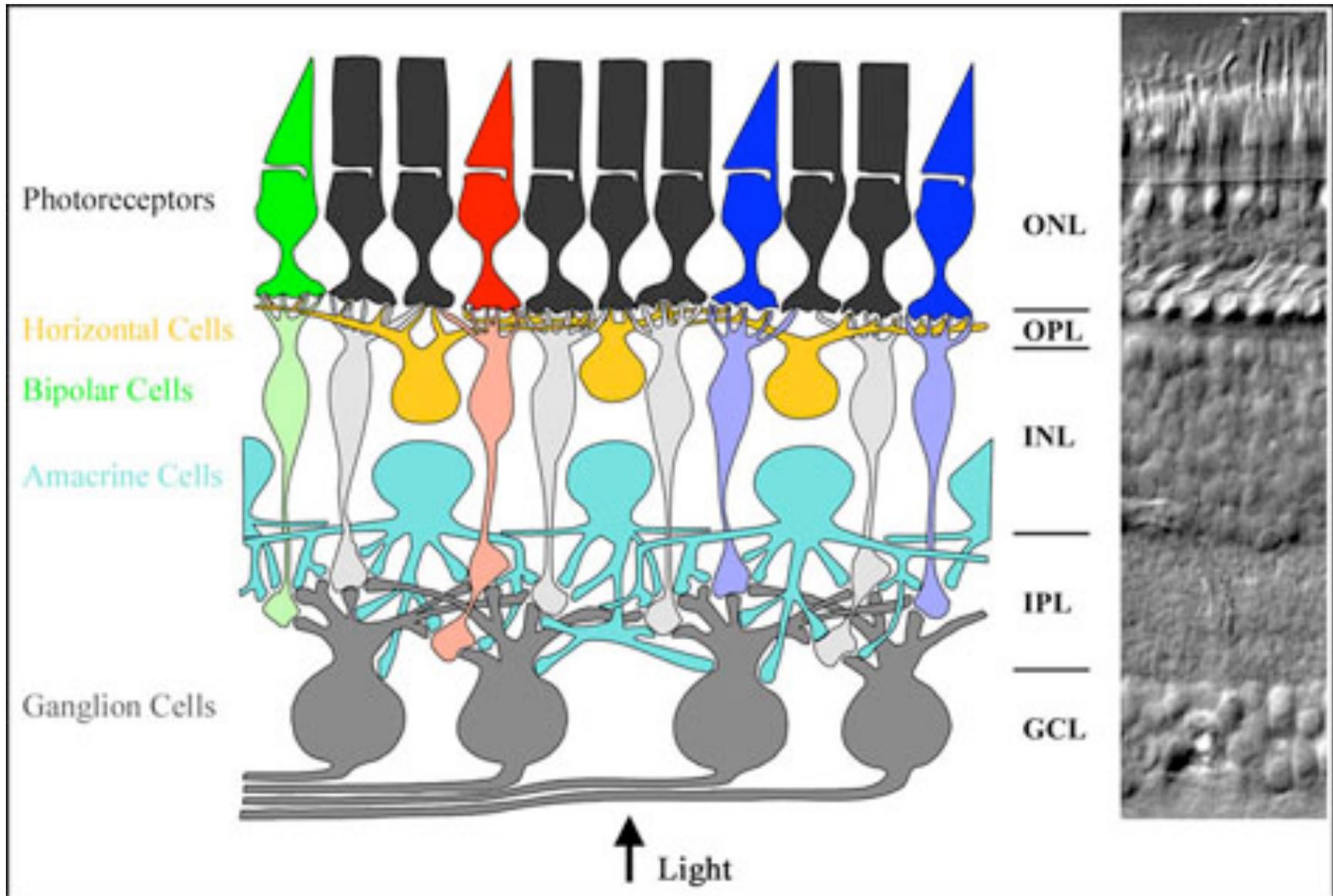


- Distributed across sensory-motor & pre-motor cortex – names are dated (Graziano 2010)
- Species-typical behaviour (again mapped); multi-modal stimuli.

# Cone or Column?



- Individual neurons must be agnostic, can't know whether they are the winner while processing.
- Winning candidates shift continuously with stimuli, posture.
- Local competitors inhibit each other (winner-take-all).

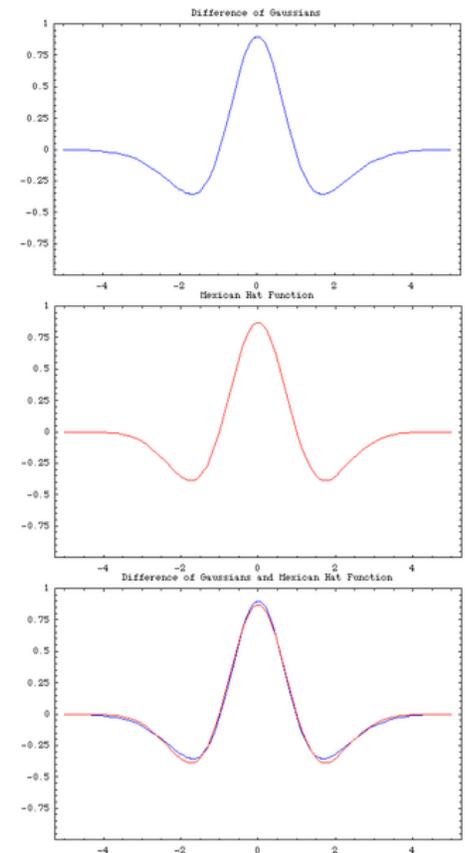
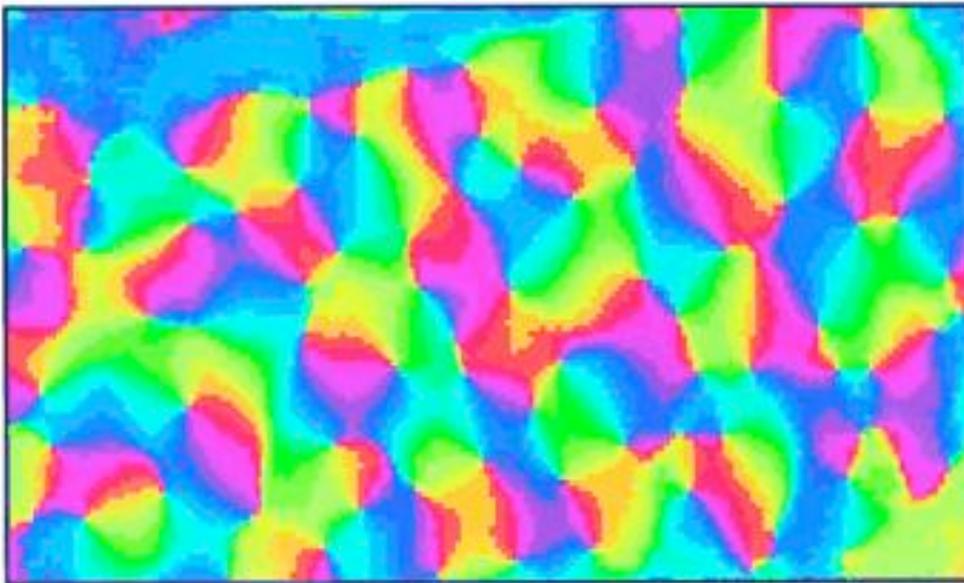


Retina again: Bipolar and Ganglian cells not only gather receptor information but locally inhibit.

# Models of Cortical Maps Built with Localised Excitation and Inhibition

Mexican hat function + Winner take all  
c.f. Willshaw, Hinton.

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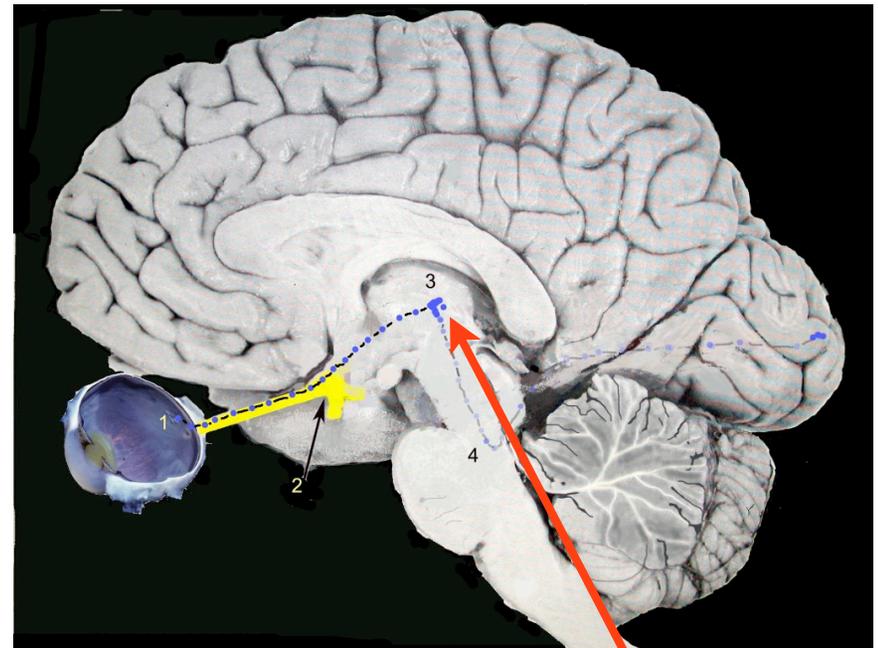


# References

- Mann's Book (linked, on line).
- Carlson, *Physiology of Behaviour* (many editions in many years, great text book.)
- Tom Mitchell, *Machine Learning*, 1997.
  - Both in Library!

# Q: Why put the visual cortex in the rear?

- More time-critical processing happens in midbrain.
- VI also processes Braille.
- Light travels faster than sound: facilitates coincidence detection.



‘reptilian’  
vision